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The present invention relates to an improved dog engagement mechanism. More specifically the present invention relates to improvements to a dog engagement system such that the corners of the dogs are protected. Dog engagement systems are mainly used on racing car gearboxes to engage and disengage gear. The present application applies to any application where rotational drive may be coupled and or decoupled to a gear, shaft or such like.

With conventional 'Dog-Engagement' systems in gearboxes it is common to experience the wear or rounding off of the corners of the dogs. Such wear can ultimately result in the loss of drive. The wear can occur upon engagement or disengagement. Upon engagement the corners of the dogs on the shaft (dog ring) can collide with the corners of the dogs on the gear thus causing damage.

Wear upon disengagement occurs if the dogs are disengaged while under load thus rounding off the corners of the dogs as they pass each other on the way out.

It is one object of the present invention to substantially overcome these deficiencies.

In accordance with the present invention there is provided an improved dog-type engagement mechanism whereby the conventional dogs are replaced with dogs that have an additional region capable of preventing the corner of the shaft dogs from contacting the corner of the dogs on the gears thus preventing wear of the corners of the dogs.

The additional region is fitted to both the shaft dogs and the gear dogs in such a way that the two new regions will collide prior to the drive corners colliding thus creating a buffer. The blunt shapes of this buffer contact are designed to last longer than a conventional corner contact.

During full lock condition recesses are provided to accept the buffer regions.

Upon disengagement the buffer region must ramp out of the recess prior to unlocking thus moving the dog corners apart during unlocking.

The preferable location of the additional buffer region is beyond the radial extremity of the dogs.

It is conceivable that the new buffer region may itself wear out thus the dogs would then function conventionally. Nevertheless they will have had prolonged life due to the period the buffers were intact.

Brief Description of the Drawings

The present invention will now be described by way of example only, with reference to the accompanying drawings, in which:

Figure 1 is a perspective view of the gear showing the dogs with the additional bumper region in accordance with the embodiment.

Figure 2 is a perspective view of a typical mating dog also with the additional bumper region.

In Figures 1 and 2 there is shown elements of a dog engagement system 10. The dog engagement system 10 comprises a gear wheel 12 and shaft dog 14. As can best be seen in Figure 1, rotatably provided about gear 12 are gear dogs 16. The shaft dogs 14 engage gear dogs 16 fixedly provided about gear wheel 12.

Rotational power may be transferred to or from shaft (not shown) by way of the shaft dogs 14 and gear wheel dogs 16 as determined by positioning of the selector assembly (not shown).

The shaft dogs 14 are axially slidable along the shaft (not shown), whilst rotating in conjunction therewith.

As can best be seen in figure 1 the gear has three dogs 16, equidistantly spaced about the circumference. When the fork (not shown) causes the shaft dog sets to slide towards the gear 12 the gear dog faces 18 lock against the shaft dog faces 20 thus causing power transmission.

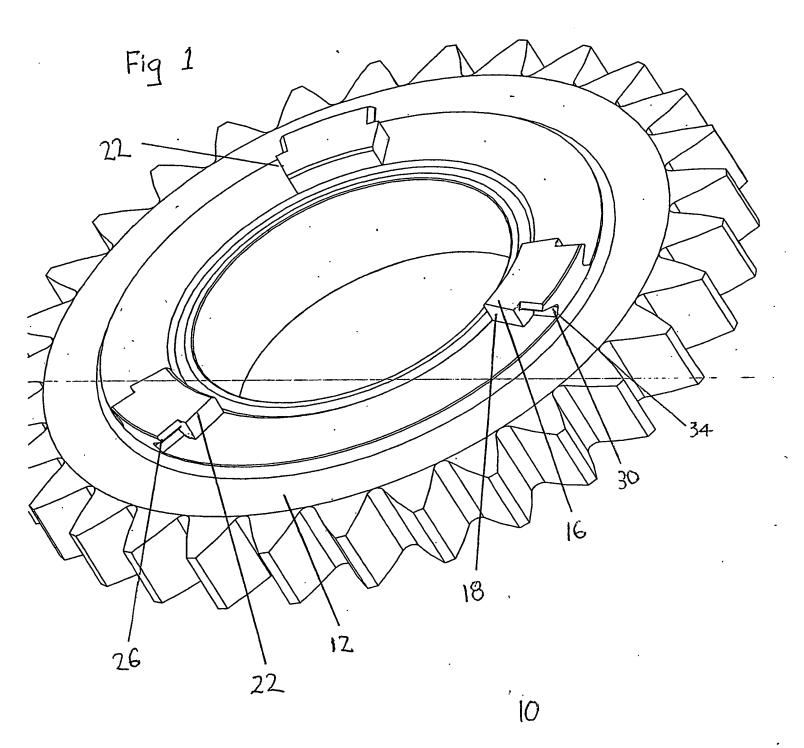
The corners 22 of the gear dogs 16 must not be able to collide with the corners 24 of the shaft dogs 14.

The corners 22 and 24 are protected by buffer regions 26 and 28.

Recess region 30 accommodates buffer 28 upon full lock.

The ramped surfaces 32 and 34 cause the corners 22 and 24 to be parted during unlocking.

Modifications and variations such as would be apparent to the skilled addressee are considered to fall within the scope of the present invention.



2/2 28 ,24 Fig 2 -20 to the second se

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